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THE FACTOR 10 CHALLENGE

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Metaphors of Cognition

Computers have been the metaphor of cognition for 50 years

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Robots have become the new metaphor over the last 10 years





Typical Robot is:

Designed for specific goal

Assembled by human/machine

Kept alive by batteries

Hardware + Software

Conventional hardware

On/off switch



Most Living Organisms:





Self-assemble and grow Interact with environment Find own energy / metabolism No brain/mind dichotomy Soft, compliant, self-healing Die only once



Fully functional physical artifacts (not simulations), which, during an extended but limited period of time (e.g., 10 months) autonomously grow:

- Cognitive abilities (IQ and sensorimotor behaviors) by at least a factor of 10;

- Body volume, thereby differentiating out organs and effectors, by at least a factor of 10



Artifacts evolving their cognition and motor control autonomously based on multimodal/multisensory feedback in a predefined and fixed body



SOME BIG CHALLENGES:

- Open-ended, online, continuous adaptation
- Architectures
- Self-assessment of performance

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Artifacts with bodies/effectors that flexibly adapt their shapes to different tasks:

- modular systems of basic elements that re-organize their structure

- robots made of materials with mechanical plasticity and a peripheral nervous system

Self-assembling robots

Molecule robot, Dartmouth College

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Polybot, Xerox Parc

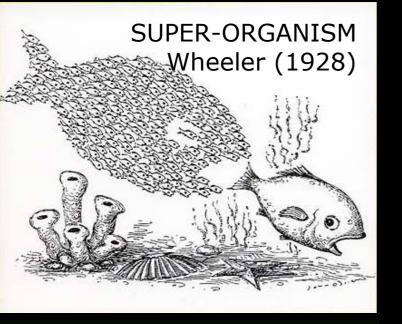
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M-Tran, AIST/Tokyo Inst. Technology

Conro, USC Information Sciences Inst.

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Super-organisms



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Gel Robot, Univ. Tokyo

- Composite polymers with deformation driven by catalytic reaction in salt water

- Shape and connectivity determine type of motion

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Type III artifacts

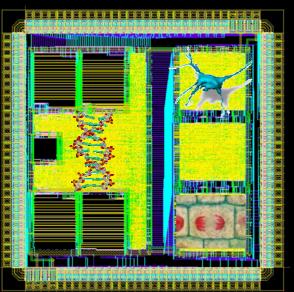
Artifacts that co-evolve their distributed brains and bodies in permanent interaction with the environment over an extended period of their lifetime



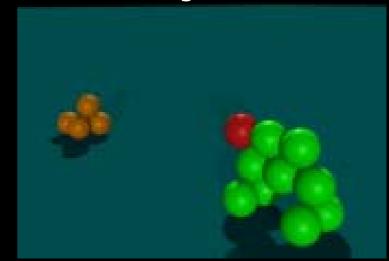
Growing artifacts



POETIC TISSUE A multi-cellular circuit capable of evolution, growth, differentiation, and neural plasticity



HYDRA A growing artefact composed of robotic cells capable of evolution, self-assembly, and self-organization



BUT:

Growth is implemented by recruiting of elements (New) use of conventional mechatronic technology No metabolism



Neuromorphic

- distributed
- adaptive
- simple

No software/hardware dichotomy

Organic circuits:

- Flexible, redundant, locally unreliable
- Growing
- Bio-degradable (degradation & death)

Analog vs. digital (digital should be emergent)



- **Open-ended** adaptation
- Behavioral and energetic autonomy (metabolism)
- Multi-cellular (vs. monolithic) systems
- Physical growth, reproduction, degradation, death
- Collaboration with material science